

Andrew Randell

B.E.Sc. Mechatronics Engineering University of Western Ontario

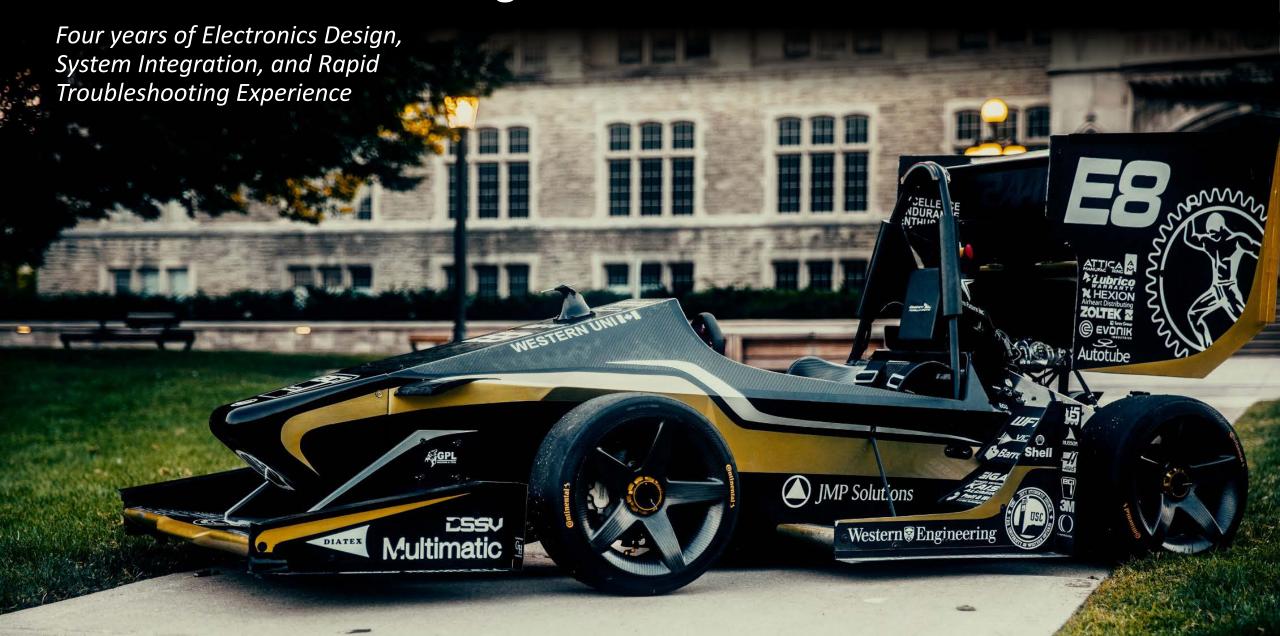
16-Months at Intel Corporation

48-Months of Formula-SAE experience



Western Formula Racing: Formula-SAE



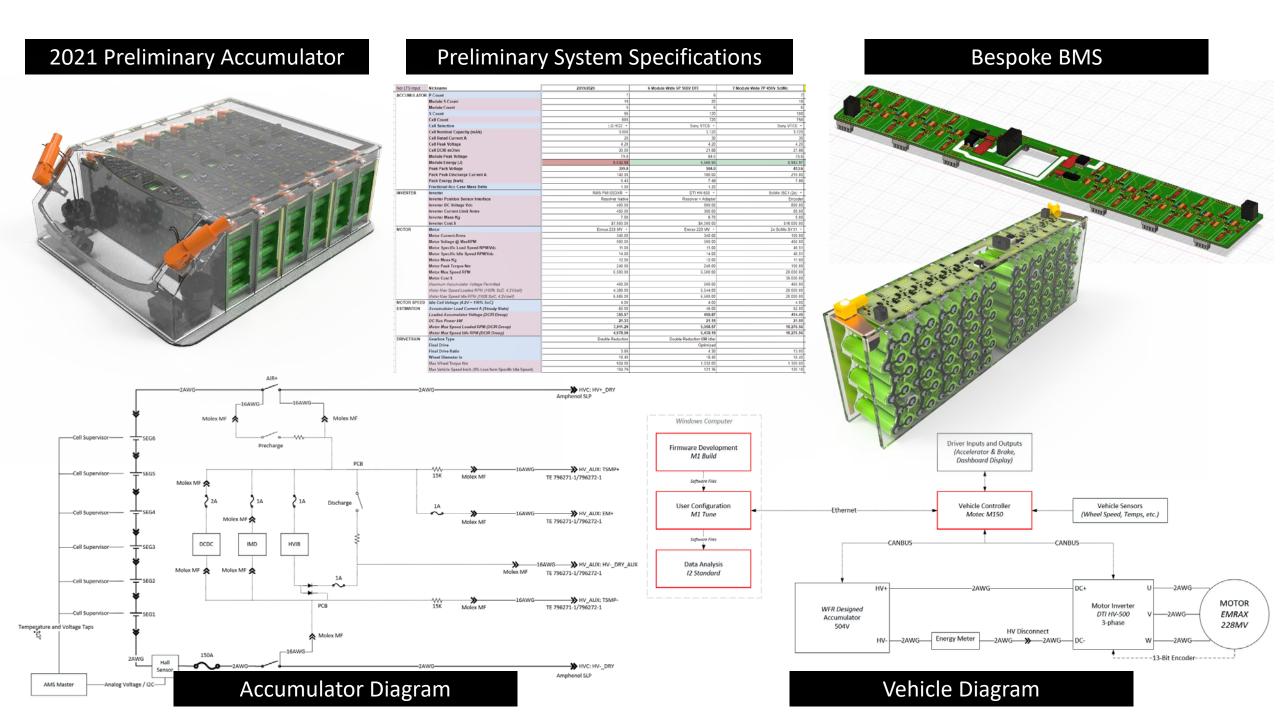




2021 WFR Electrical Director

- One of three team leaders responsible for 50+ team members and 10 subsection leads who design, build, and race a 504-volt, \$160,000 electric vehicle at international SAE competitions
- Administered vehicle propulsion system design from the ground up for the 2021 vehicle. Increased the system efficiency by 30% with accumulator cell arrangement optimizations, and integrating an allnew motor controller
- Designed a Bespoke Battery Management System with hardware and control algorithms to manage 720 Lithium-ion battery cells arranged in a 6P120S configuration
- Managed cross-functional meetings and workgroups for team members. Mentored junior team members



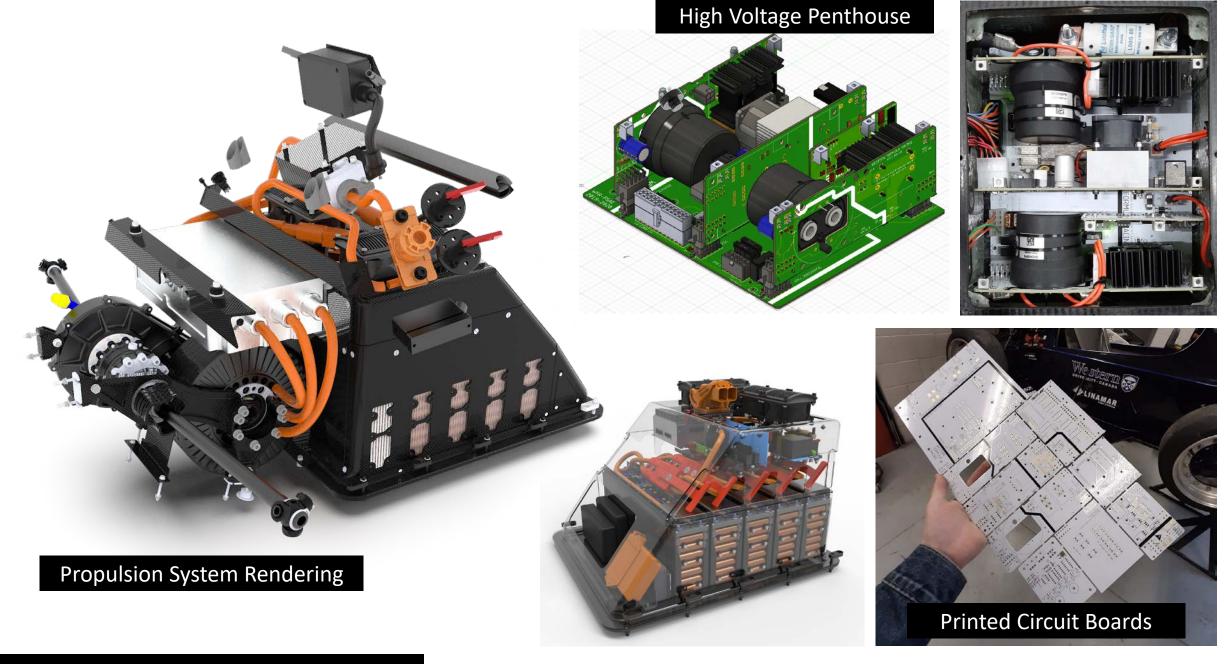


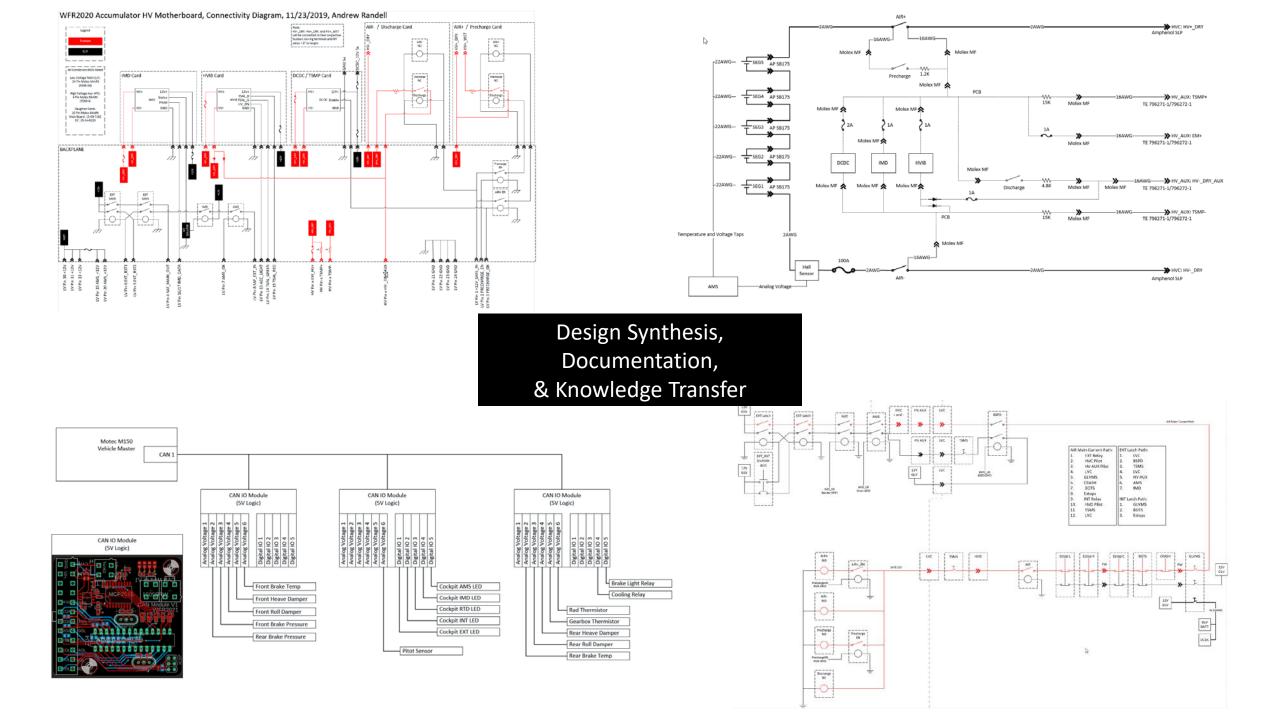


2020 WFR Energy Accumulator Lead

- Lead electrical system design and assembly for a 400-volt energy Accumulator. Incorporated all discrete control components to a modular PCB assembly, resulting with stellar accumulator reliability and serviceability allowing the vehicle to complete the season with no serious faults
- Assembled and tuned a Cascadia PM100DXR inverter and Emrax 228MV motor used in the propulsion system
- Designed a 400V to 12V DCDC converter based on Vicor DCM modules to power the vehicle's low-voltage systems







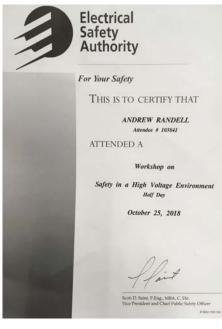




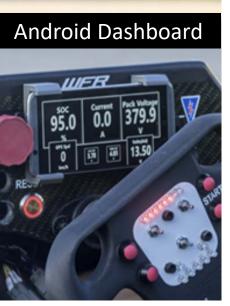
2019 WFR Low-Voltage & Data Acquisition Lead

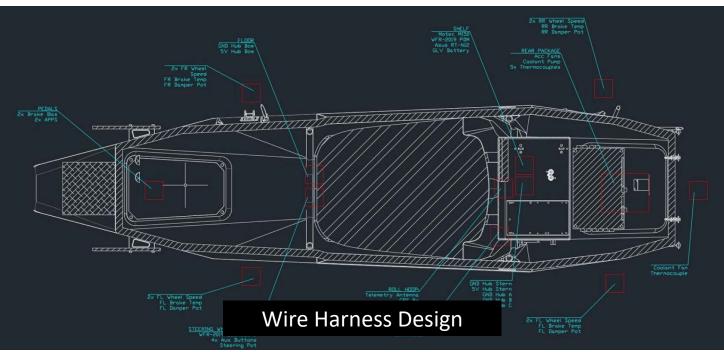
- Acted as the Certified High Voltage Electrical Safety Officer for the \$150,000 vehicle and 55+ member team
- Lead low-voltage harness design and assembly utilizing a bespoke Power Distribution Module with telemetry, an Android-based dashboard display with OBDII, and a Motec M150 engine controller and DAQ

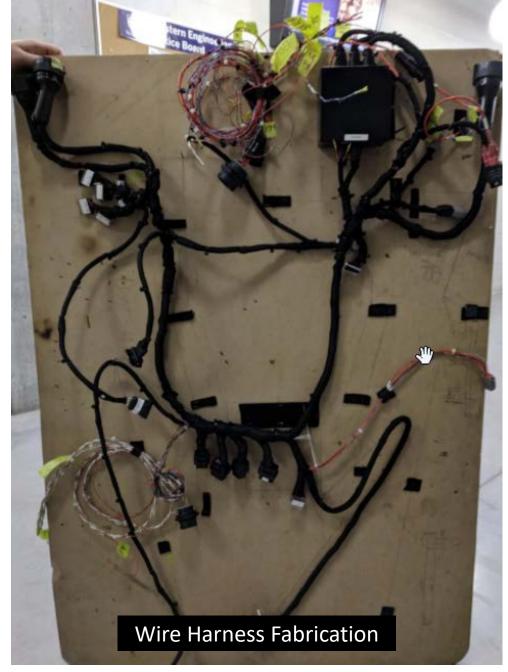












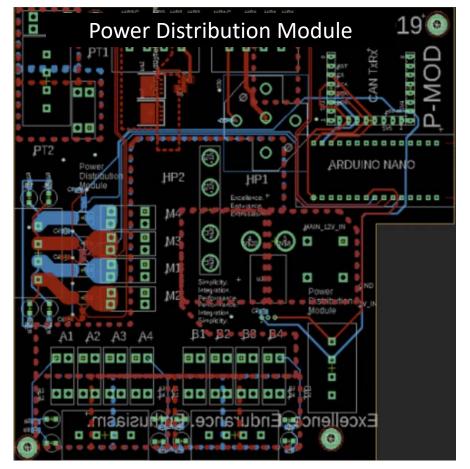


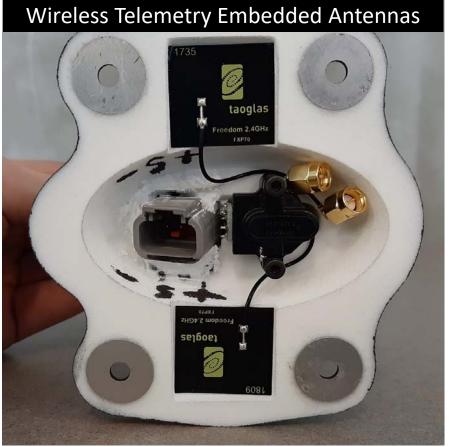


2018 WFR Electrical Member

- Incorporated wireless telemetry based on a generic 802.11n local area network with a router running OpenWRT
- Supported the electrical team with duties including: system design, wire harness assembly, and troubleshooting















Product Marketing, Drone Photography, and Creative Content

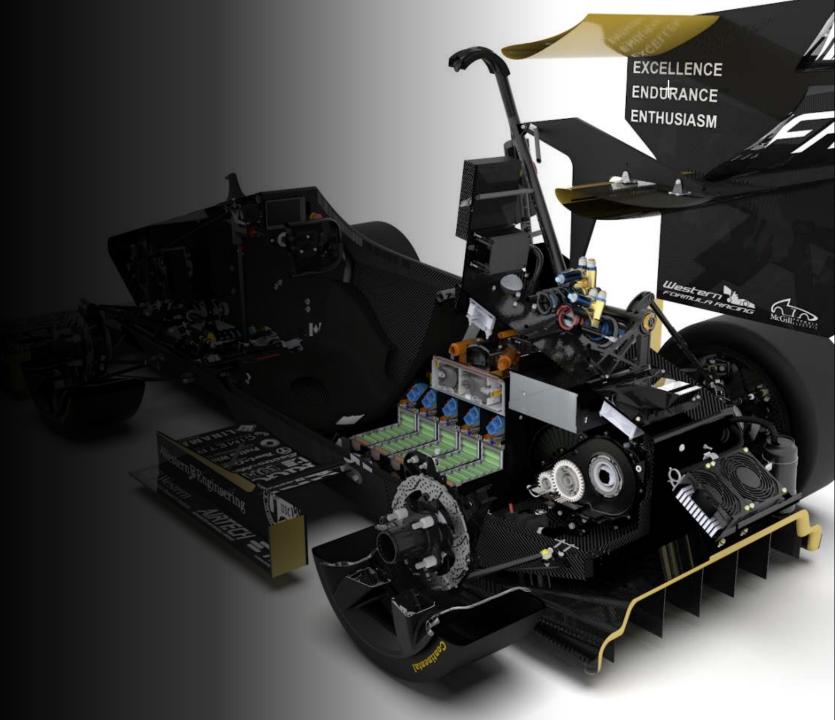
Photorealistic renderings of Solidworks models via Keyshot

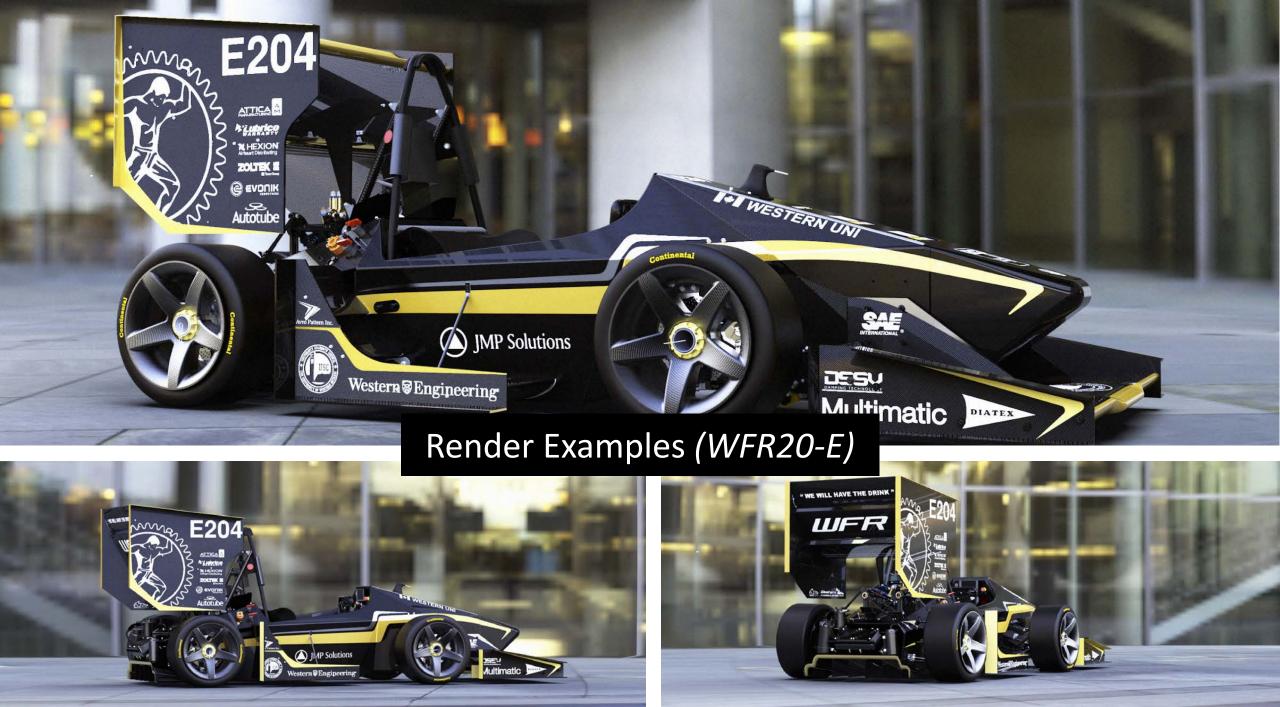
Tunable and spherical product renders

- Spherical Interactive Render
- Section View Interactive Render

Video editing and production

- WFR20-E Year in Review Video
- WFR20-E Testing Montage Video





Professional Experience

24-months of Professional Internship and Co-op Experience







Intel Corporation 16-month Internship

Platform Architect and PCB Designer

- Lead architecture and design for a high-speed silicon validation platform to be scaled across Intel validation teams
- Designed prototype PCBs to improve platform bringup and validation efficiency in a laboratory setting
- Incorporated CPLD devices for system housekeeping tasks resulting in PCB layout area and cost reduction
- Implemented ECAD processes and tools to increase design workflow efficiency
- Managed Intel's relationship with third-party vendors for specific platform subsystems and exploratory projects
- Submitted two patent applications for system behaviour during power state transitions





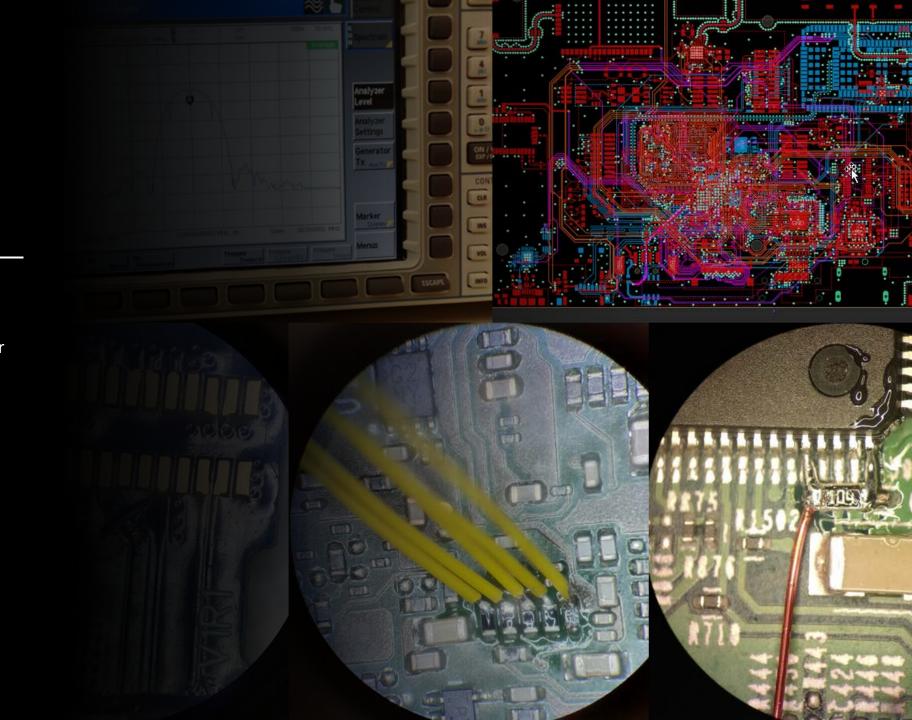
Swift Labs 8-month Co-op

Term 2: Hardware Designer

- PCB component selection, schematic capture, and board layout alteration for an IoT gateway
- Hardware debug, rework, and bring-up coordination for an IoT gateway in a laboratory setting

Term 1: Firmware Developer

- Automated wireless testing and verification procedures via remote control of lab testing equipment over GPIR
- Specified and compiled Buildroot Linux firmware for a production IoT gateway



Technical Skills

Design Tools

- OrCAD
- Allegro PCB Layout
- DE HDL Schematic Capture
- Eagle PCB
- MATLAB and Simulink
- Excel
- LTSpice
- PowerDC
- Solidworks (CSWA)
- Git & Github
- Python
- C++

Prototyping

- Oscilloscope
- Logic Analyzer
- SMD Soldering
- Arduino
- 12C, SPI
- CANBUS
- High-voltage wiring
- 3D Printing

Creative & Office

- Adobe Creative Suite
- Keyshot Rendering
- MS Office
- LaTeX



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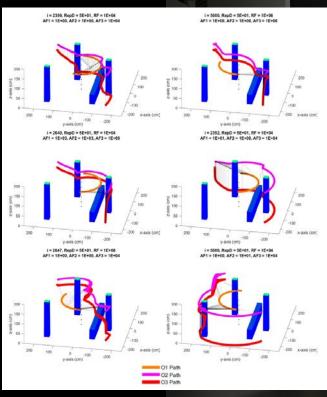


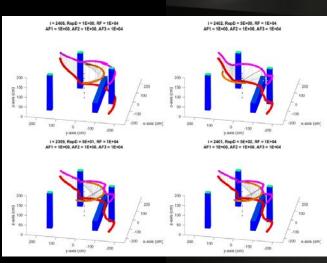




MSE4401 Path Planning

- Develop Code to control a robotic arm
- Move objects between positions
- Quintic Interpolations
- Gradient decent implemented in MATLAB



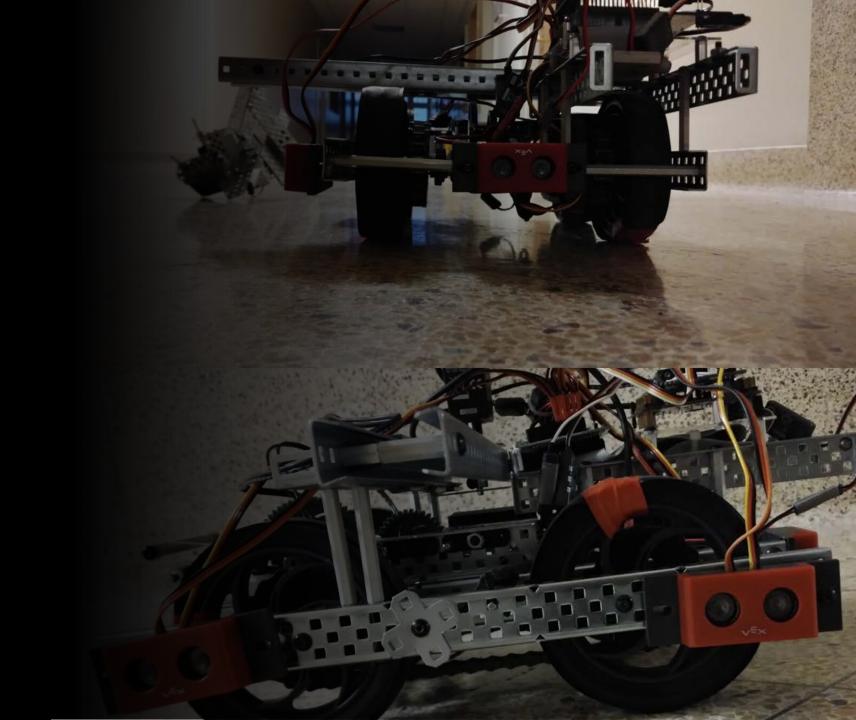




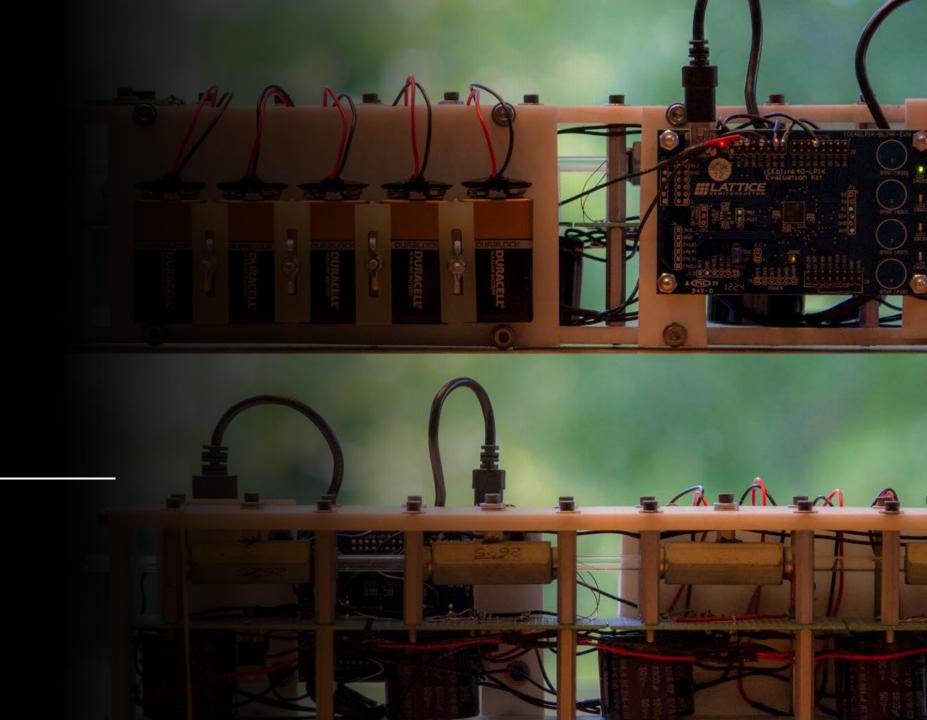


MSE2201 Autonomous Robot

- Develop an autonomous robot to navigate a course
- Detect and pick up objects
- Deposit objects in the proper location

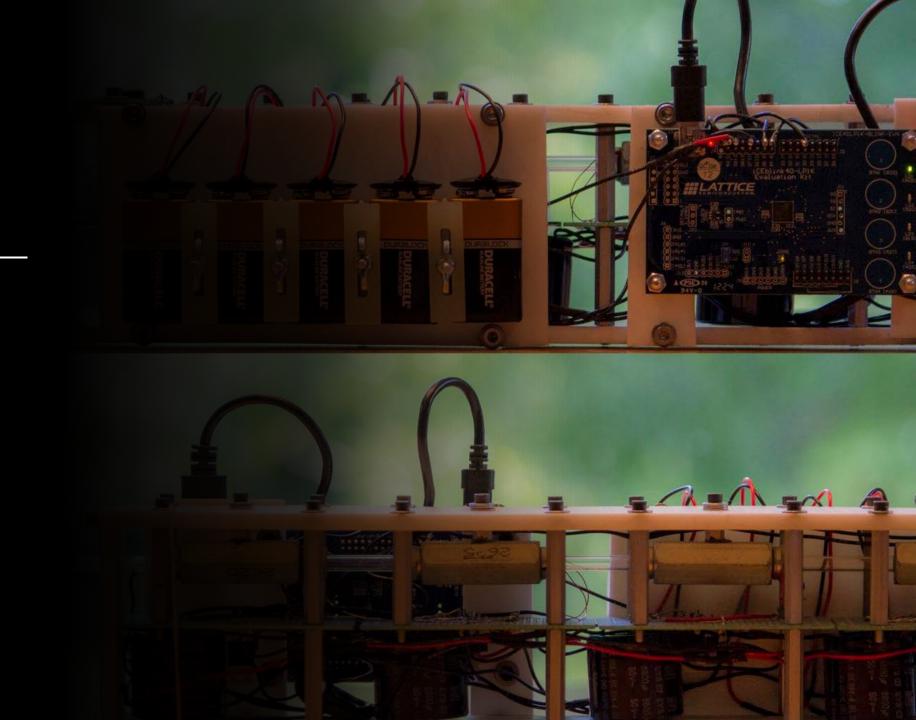


Personal Projects



Home-built Linear Accelerator

- Four-stages
- 6800uF Caps
- 48V
- MOSFET Switches
- FPGA Controlled
- YouTube Video



Computers and Networking

- Built several desktop PCs for personal and business use
- Manage a FreeNAS media server and NAS for personal use
- Set up several local area networks with multiple access points
- Portfolio site: andrewrandell.ca
 - Hosted on Github Pages
 - Modified HTML5 template



